KCM- 91WT Temperature Controller Instruction Manual

1. Features:

1.1.Input Sensor Types

Can be connect the following sensors and signals to the universal input.

Thermocouple (temperature input): K, J, T, E, S,R

Resistance thermometer (temperature input): Pt100, CU50

1.2.Control Outputs

A control output can be voltage output (for driving SSR) or Relay contact: 250 V AC, 3 A (Resistive load). depending on the model.

1.3.Adjusting PID Constants

Can be easily set the optimum PID constants by performing AT (auto-tuning) with the limit cycle method. 1.4.Standard Alarms Relay contact: 250 V AC, 3 A (Resistive load).

Can be output an alarm when the deviation, process value, set point, or manipulated value reaches a specified value.

1.5 Sampling Time: 0.5 sec

1.6.Use this controller within the following allowable range:

Allowable ambient temperature: -0 to +55 °C

Allowable ambient humidity: 5 to 85 % RH.

2. Dimensions:

160×80mm panel cutout :152×76mm

96×96mm panel cutout :92×92mm

96×48mm panel cutout :92×44mm(horizontal)

48×96mm panel cutout :44×92mm(vertical)

72×72mm panel cutout :68×68mm 48×48mm panel cutout :44×44mm

88×107×59mm DIN 35 rail mounting socket

2. Parts Description:



Terminal Arrangement



This wiring diagram is offered for example purposes only.

1 ALM1: lamp Lights when Event occurs

3 AT lamp: Flashes during Auto-tuning (AT)

5 PV display: Displays Measured value (PV) or various Parameter symbols

2 TE lamp: Lights when The countdown works.

4 Output lamp: Lights when output is turned on6 SV display: Displays segment level, Set value (SV),

Manipulated output value (MV) or various Parameter set values.

7 Up key:

8 Down key:

-Increase numerals.

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-Decrease numerals

- To scroll through numbers faster, press and hold the Up key.

9Shift key: Shift digits when settings are changed. **10 Set**

10 Set (SET) key: Used for Parameter calling up and set value registration.

3. Parameters

ID	CODE	Name	Setting range	Manual	Defaults
0	SP	Setting value	Determined by	Set the temperature set value (SV) which	50.0
			P-SL P-SH	is the target value for control	
				refer to "In L"	
1	25	setting value of	1∼99 : 99	have to shorted "RESET",	10
		the timer		The countdown will work.	
		Alarm Setting	Determined by P-SL P-	refer to ALP for the alarm mode suitable.	
2	RL I	value			100
		Proportional Band	0~200.0	Set when PI or PID control is performance. For	
3	ρ			action.	8.0
				When P=0,the controller is ON/OFF control	
		Calculus time		Eliminates offset occurring in proportional	
4	1	-	0~3000S	control.	240
5	d	Differential time	0∼200S	Prevents overshoot and/or undershoot	30
				caused by integral action effect.	
6	RE	Auto tuning	ON: Auto tuning (AT)	Turns OFF automatically when the AT with	OFF
		Ũ	start	learning function is completed.	
			OFF: Auto tuning (AT)		
			stopped		
7	E	Control time	2~120s	Proportional cycle time	20
8	НУ	Differential gap	0.1~100.0	When the control is ON/OFF control(P=0)	1.0
		-		If measured value (PV) is near the set	
				value. the differential gap setting can prevent	
				the relay contact from ON or OFF repetition.	
9	KY 1	Alarm Differential gap	0.1~100.0	If measured value (PV) is near the alarm set	1.0
				value. the differential gap setting can prevent	
				the relay contact from ON or OFF repetition.	
10	РЬ	PV Bias	±20.0	The value set in the PV bias is added to the a	0
				correct the input value.	
		Digital Filter		This is a filter by software prepared in order to r	
11	FILE		0~50	measured value (PV) by noise.	20
12	Loce	Set data lock	0~50	LOCK=0, all the parameter can be set.	0
				Otherwise, all the parameter can't be set	
	_	Input type	CU50 (נטלט),	CU50、PT、K、E、J、	
13	50		РТ100(<i>РЕ</i>), К (Е),	Τ、S	J
			$E(\boldsymbol{\xi}), J(\boldsymbol{j}), T(\boldsymbol{\xi}),$		
			ג) (כ) צ		
14	P_58	Input range high	P-SL~1800	The control is displayed after the Input type	900
15	P_SL	Input range low	-199.9 ~ <i>P</i> -SH	and Input range.	0
16	outX	Output limiter high	OUTL~100.0	The min value and max value of output	100.0
17	outl	Output limiter low	0.0~OUTH		0.0
18	RLP	Alarm type	0~1	0: Alarm function OFF;	0
				1: Process high alarm;	
				2:Process low alarm;	
				3: Deviation High alarm ;	
				4: Deviation low alarm;	

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19	FEb	Time unit	0~1	0: Minutes .seconds 1: Hour.minutes	0
20	Lool	Hot/Cold	ON/ OFF	Off:reverse control(heating)	OFF
				On:positive control(cooling)	
21	oP_R	Output type	—	SSR: Solid state relay,RLP:Relay	-
22	oPPO	Initial output	0~100	Output initial value	0
23	[F	PV unit	C/F	C: Celsius F: Fahrenheit	С
24	d٩	Decimal point	ON/ OFF	ON. decimal point; OFF. no decimal po	OFF
25	Int	Countdown	0~3	It will work after being powered on again.	0
		function			

3.2About Countdown function

0	Without timer
1	When the measured value reaches the setting value, the setting time starts to decrease, once the time decreases to the te relay closes and the out relay is working
2	When the measured value reaches the setting value, the setting time starts to decrease, once the time decreases to the te relay closes and the out relay is stopped
3	When the controller is powered on, the setting time starts to decrease, once the time decreases to zero, the te relay c

4. Operation



4.1 Basic Setting Level:

Press the key SET 3 seconds to enter into the main Parameters, the controller will display the Parameter code($1 \sim 25$)in the window at the upper tube, and display the Parameter data at the lower tube. Press Key \blacktriangle , \checkmark or \blacktriangleleft to adjust the Parameters, and then press the Key SET to preserve.

It will be preserved of the data and withdrawal of the setting with no any operations automatically within 10 seconds.

Electronics Lock. All the Parameter can be revised when Lock=0; Only the "SP" can be revised when Lock=1.

4.2Setting value Level:

Press the key SET 1 seconds to enter into the SV Setting Mode. When the operation mode is the Auto-tuning mode, the Set value (SV) can be set.

4.3Manual Control Operation:

Press the ◀ key about 3S enter into the manual regulation, it will display "H" at the lower row, in this time can set the output power; press the ◀ key about 3S again it will withdraw the manual regulation.

5. Determining PID Constants(Auto-tuning)

When AT is executed, the optimum PID constants for the set point at that time are set automatically. A method (called the limit cycle method) for forcibly changing the manipulated variable and finding the characteristics of the control object is employed.

Set the HY is $0.5 \sim 1^{\circ}$ C, if the output is relay set the t=10S, then set the AT=1, the lamp of AT will be flashed, in this time the controller enter into **Auto-tuning**. now meter's control way is on-off mode, after 3 times vibrating(3 control period) automaticlly save P, I, D parameter, the self-adjusting procession finished.

Operation will be as shown in the following diagram:

Attentions:

-When Auto-tuning, the controller should not change the set value.

-When the power off during Auto-tuning, it will restart Auto-tuning next time.

-When it need artificially exit during **Auto-tuning**, set the Parameter(AT) to 0 so that can exit, but the setting result will not be valid.

6. Alarm (ALM) function:

Alarm (ALM) function	Alarm status[ON]	Alarm status[OFF]			
Process high alarm	Measured value>Alarm set value	Measured value <alarm set="" td="" value<=""></alarm>			
Process low alarm	Measured value <alarm set="" td="" value<=""><td>Measured value>Alarm set value</td></alarm>	Measured value>Alarm set value			
Deviation high alarm	Measured value>Alarm set value + Set value	Measured value>Alarm set value + Set value			
Deviation low alarm	Measured value <alarm -="" set="" td="" value="" value<=""><td>Measured value>Alarm set value - Set value</td></alarm>	Measured value>Alarm set value - Set value			

Character Symbols: This	s manual indicates 9-segmen	t display characters	as shown below.
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Α	В	С	D	E	F	G	Н	I	J	Κ	L	М
R	Ь	Ε	б	Ε	F	6	Н	1	7	Ľ	L	۱c
Ν	0	Р	Q	R	S	t	U	Y	Т			
n	0	ρ	9	r	5	Ł	U	Ч	Г			